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10569 U.S. PTO

<b>PROVISIONAL PATENT APPLICATION UNDER §111(b)</b>	<i>Attorney Docket No.</i>	091395-9427
	<i>First Named Inventor</i>	
	Mark A. Joki	
	<i>Express Mail Label No.</i>	ET684382909US

22154 U.S. PTO  
60/546854



Mail Stop PROVISIONAL PATENT APPLICATION

Commissioner for Patents

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Sir:

Enclosed for filing is a complete provisional patent application entitled "LOW DRAG MULTIMODE CLUTCH" invented by:

Mark A. Joki  
5930 North American Road  
Dover, Ohio 44622

and including the following documents:

Specification - 5 pages  
Abstract of the Disclosure  
Drawings - 2 sheets  
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Respectfully submitted,

Glenn M. Massina  
Reg. No. 40,081  
Michael Best & Friedrich LLP  
3773 Corporate Parkway, Suite 360  
Center Valley, Pennsylvania 18034

Date: February 23, 2004  
cc: Docketing  
Wkg Atty. GMM  
Resp Atty. DBS

## LOW DRAG MULTIMODE CLUTCH

### BACKGROUND

5           The present invention relates to a clutch device. More particularly, the present invention relates to a multimode clutch device.

          Planetary gear automatic transmissions employ one-way clutches to simplify shifting. If a first planetary stage is transmitting power through a one-way clutch, a parallel connected second stage with a higher ratio can be engaged during a shift. The one-way clutch allows the  
10       output speed to increase without the first stage resisting the increased speed. The first planetary stage is however incapable of carrying negative torque because of the one-way clutch. If the one-way clutch can be selectively locked, additional ratios can be designed into the transmission without adding additional planetary stages. US patent 6,409,001 discloses a full complement multimode clutch that is capable of providing selectable one-way forward, one-way reverse,  
15       freewheeling, and locking modes. This clutch relies on a 'slipper' ring which must rub against a mating surface to provide a lockup. The present invention avoids the frictional losses of the slipper clutch in a freewheeling mode while still allowing mode control.

### SUMMARY

20           The present invention provides a clutch device comprising a first member, a second member, an outer race, and a slipper. The first member has a conic inner periphery and the second member has a conic outer periphery. The outer race is fixed to the conic inner periphery of said first member and the slipper is positioned about the conic outer periphery of the second member. The outer clutch race has multiple longitudinal projections on its inner peripheral

surface corresponding to similar projections on the outer peripheral surface of the slipper to define pockets into which rollers are arranged. The slipper has an inner peripheral surface matable with the conic outer periphery of said second member. The axial relationship of the first and second members is adjustable to control mating between the slipper and the conic outer periphery of the second member and thereby enable or prevent torque transmission between the first and second members.

In at least one embodiment, the second member is a portion of a planet carrier of an planetary gear stage.

In a preferred embodiment of the present invention, the axial relationship between the first and second members is biased by spring force to prevent engagement and hydraulic actuation is utilized to overcome the spring force to cause engagement.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a sectional view of a planetary reduction stage employing a device according to a first embodiment of the invention.

Figure 2 is a sectional view of the slipper clutch components of Figure 1.

Figures 3a-c are sectional views of the assembly steps of a preferred method of assembling the device according to the first embodiment of the invention.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present invention will be described with reference to the accompanying drawing figures wherein like numbers represent like elements throughout. Certain terminology, for example, "top", "bottom", "right", "left", "front", "frontward", "forward", "back", "rear" and

“rearward”, is used in the following description for relative descriptive clarity only and is not intended to be limiting.

Referring to Figure 1, a planetary reduction stage within a housing 1 comprises a multiplicity of planet gears 2 supported by planet carrier 3 by way of support pins 4 and engaged to a sun gear and ring gear (not shown). The planet carrier 3 is rotatably supported by bearings 8 and 9. Onto the planet carrier 3 is formed a conic outer peripheral surface 6 which preferably has a shallow angle. The angle is preferably in the range of 1-3 degrees, preferably 1.5 degrees, but can be of an angle less than 1 degree or greater than 3 degrees. Radially outward from the conic surface 6 is a outer body 12 rotatably supported in the housing 1 by bearing surfaces in the housing 1. Said outer body 12 includes a conic inner peripheral surface of angle similar to surface 6 onto which is fixed a ring shaped clutch outer race 13. A ring shaped slipper 11 is located radially inward from the outer race 13. While the preferred embodiment is described with the ring shaped clutch race fixed to the outer body 12 conic surface with the slipper positioned radially inward, it is also considered that the components may be reversed, with the ring shaped clutch race fixed to the conic surface 6 and the slipper positioned radially outward.

Referring to Figure 2, on the inner periphery of the outer race 13 and into the outer periphery of the slipper 11 are formed longitudinal projections 20, 22 radially opposing each other. These projections 20, 22 form pockets 24 into which cylindrical rollers 14 are placed. The slipper 11 has an opening 21 cut parallel to the slipper's 11 axis to facilitate radial contraction. The slipper 11 is manufactured to a diameter slightly larger than it's mounted size to apply a radial preload force to the rollers 14. The outer race 13 and slipper 11 are generally uniform in section along a longitudinal section. Referring back to Figure 1, the outer race 13 and slipper 11 have flanges 26, 28 formed at the extremes of their widths to contain the rollers 14.

The axial location of the planet carrier 3, in its free state, is determined by roller bearing 8 which is located by a shoulder 30 in a generally cylindrical projection from the housing 7 and a spring 10. In this free state, the slipper 11 is free of the conic outer surface 6 with a small clearance, about 40-80 microns, allowing low drag rotation of the planet carrier 3. A plate clutch 5 can cause torque transmission between the outer body 12 and the housing, 1. When such torque transmission is desired, hydraulic pressure is applied to the left side of piston 15, moving it against retraction spring 16 until it contacts the planet carrier 3 and moves the planet carrier 3 right against spring 10. The slipper 11 now rubs against the conic surface 6. The tangential force carried through the rollers 14 causes them to climb the sides of their pockets 24, contracting the slipper opening 21 until the slipper 11 stops against the conic surface 6. When the clearance is removed, the rollers 14 are contacting the races at a pressure angle of 83 to 88 degrees which causes locking of the slipper 11 on the conic surface 6 and a high torque transmission capability.

To accomplish an upshift, the pressure on the piston 15 is removed, causing the piston 15 to retract under force from spring 16. However, because of the high forces of the slipper 11 on the conic surface 6, the planet carrier 3 remains in the engaged position. A clutch elsewhere in the transmission applies torque to a higher gear stage causing a reduction in torque to the subject planet stage with the slipper clutch. As torque reaches zero, the contracting force from the rollers 14 on the slipper 11 disappears, and the slipper 11 expands under its prestress. With the slipper contact relieved, the planet carrier 3 moves away from the slipper 11 by force from spring 10 and the low drag freewheeling mode is active.

Referring to Figures 3a-c, a preferred method of assembly is shown. Referring to Figure 3a, the device is assembled by first installing the outer race 13 into the outer body 12 and the

slipper 11 over the conic surface 6, then placing the outer body 12 around the slipper 11.

Referring to Figure 3b, the rollers 14 are placed between the outer race 13 and the slipper 11.

Referring to Figure 3c, a split disk tool 17 is placed in the axial gap between the outer body 12 and the planet carrier 3 to resist the force of crimping the ends of the slipper 11 and the outer

5 race 13, thereby restraining the rollers 14.

ABSTRACT

A clutch device comprising a first member, a second member, an outer race, and a  
slipper. The first member has a conic inner periphery and the second member has a conic outer  
periphery. The outer race is fixed to the conic inner periphery of said first member and the  
5 slipper is positioned about the conic outer periphery of the second member. The outer clutch  
race and the slipper have complementary projections to define pockets into which rollers are  
arranged. The axial relationship of the first and second members is adjustable to control mating  
between the slipper and the conic outer periphery of the second member and thereby enable or  
prevent torque transmission between the first and second members.



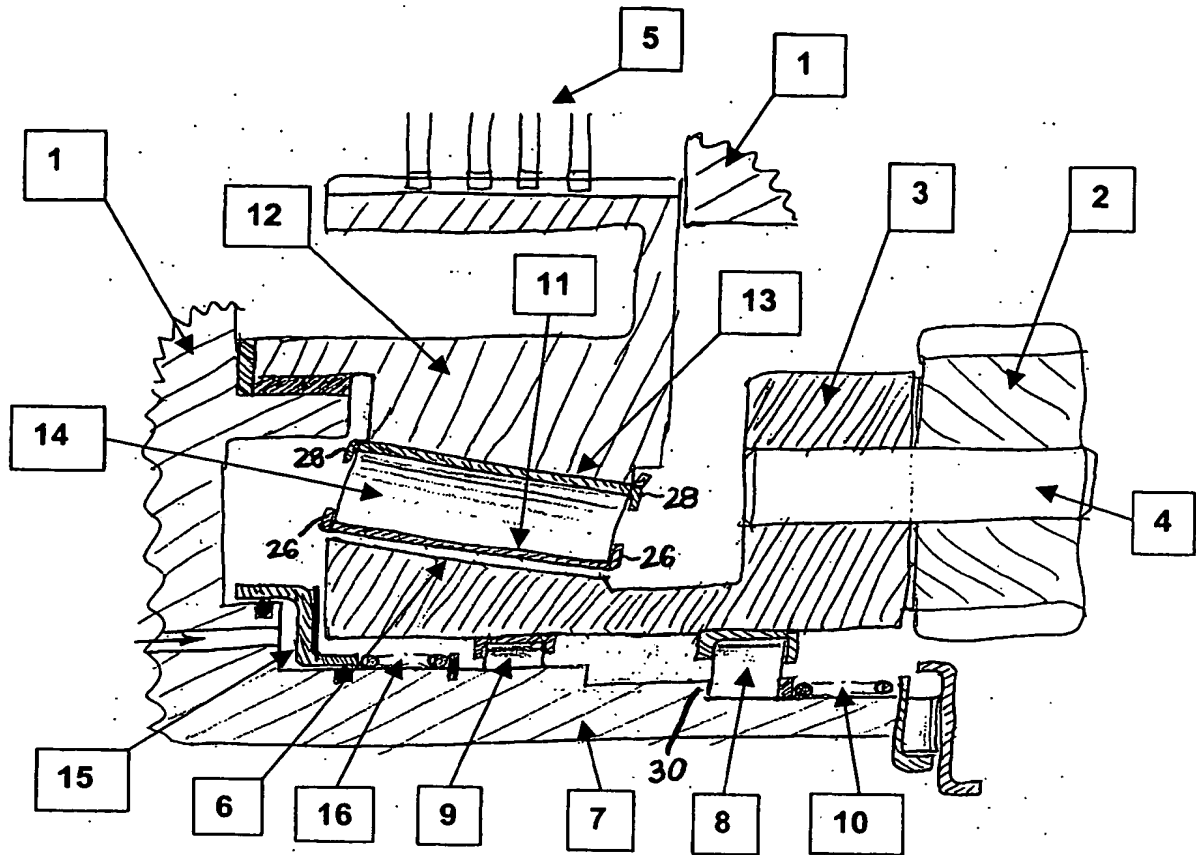


Figure 1

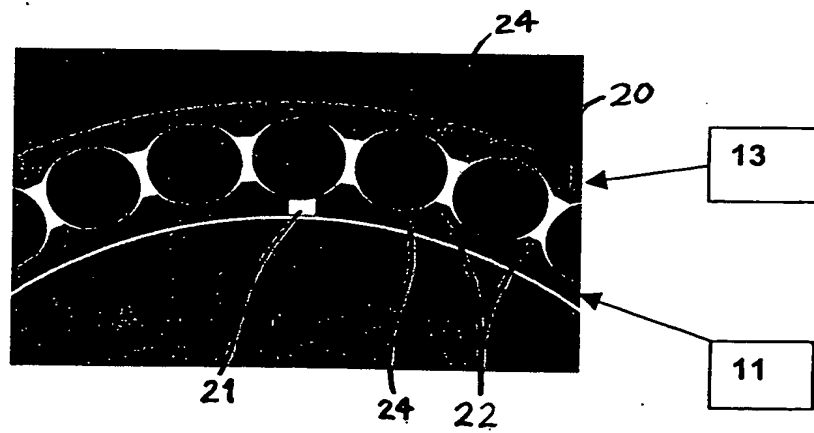


Figure 2

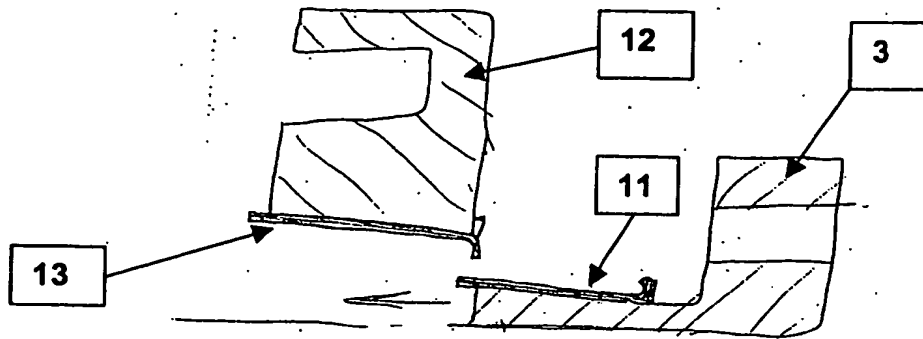


Figure 3a

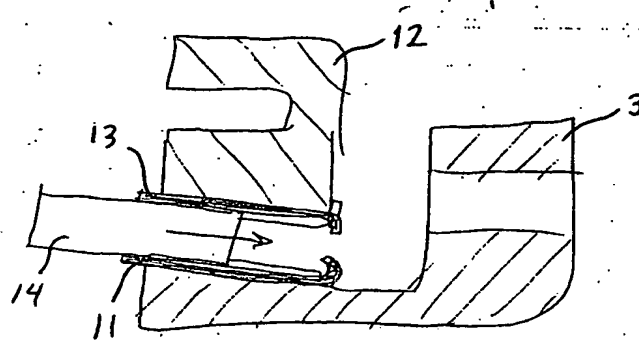


Figure 3b

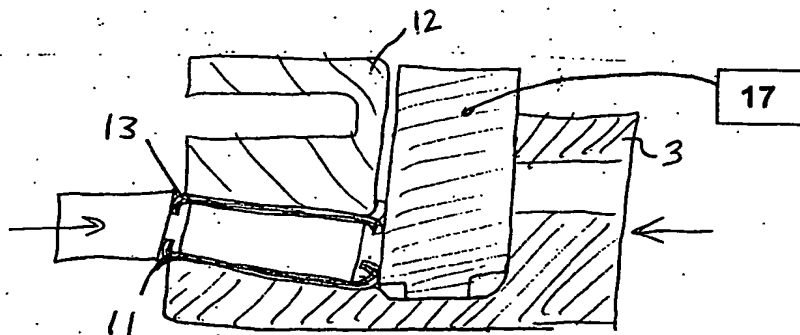


Figure 3c

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